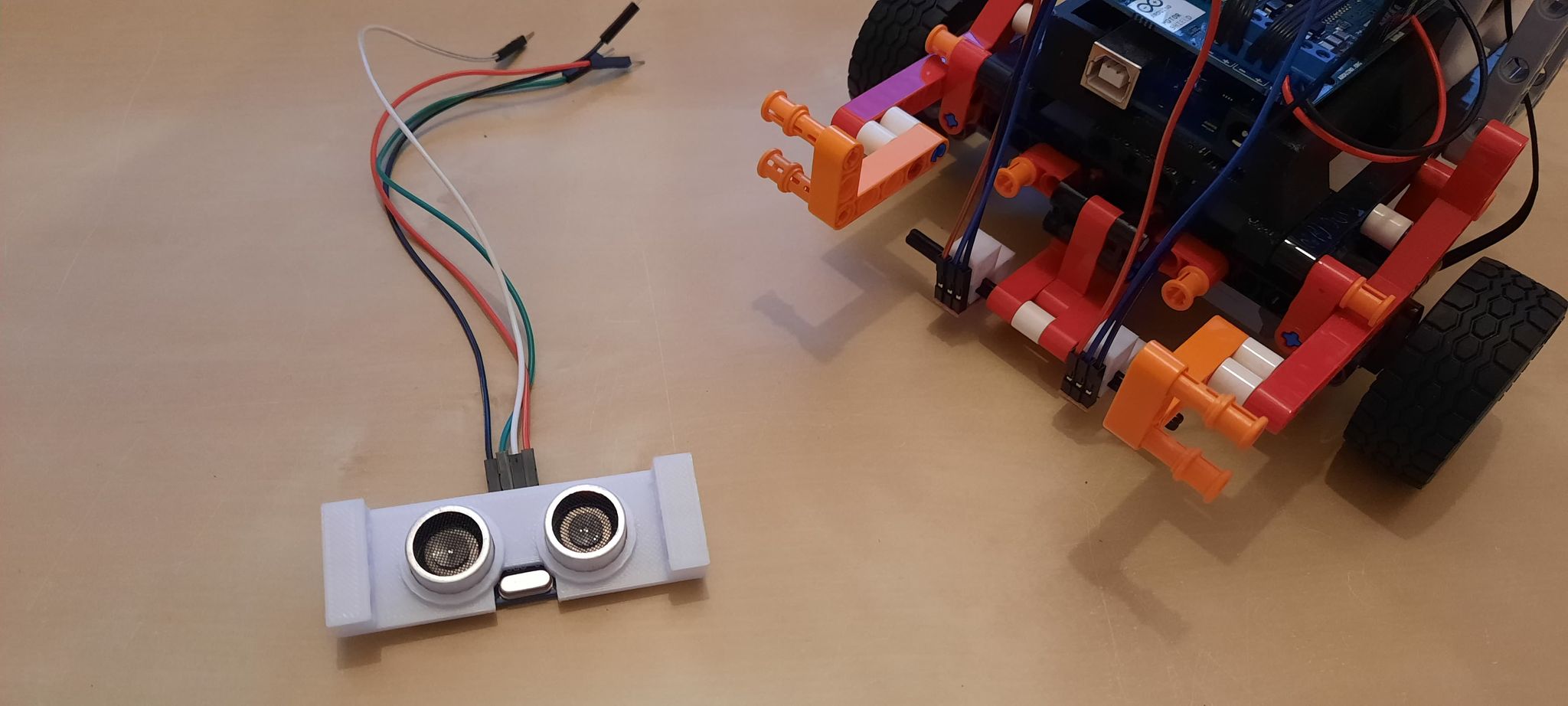
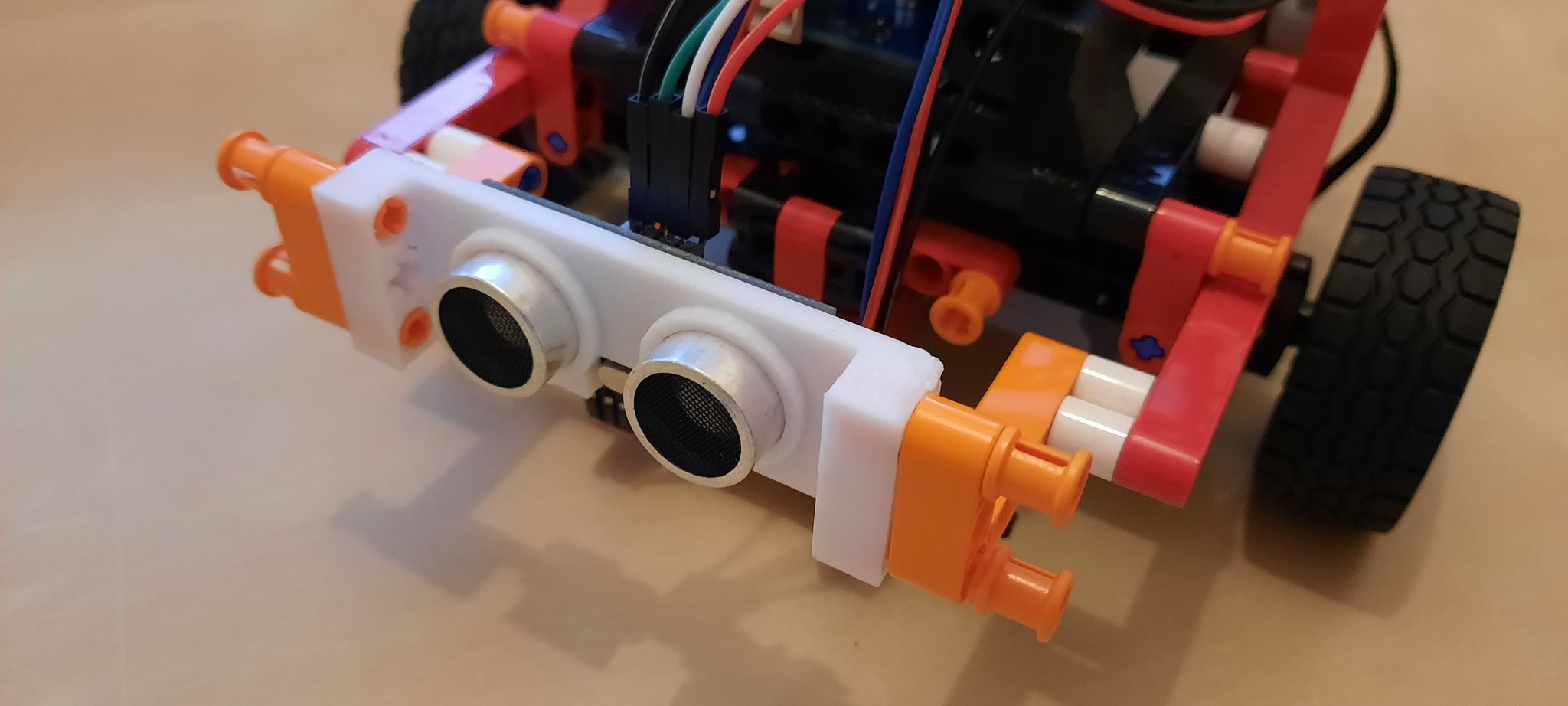
# Transporter – Integrate IR-Sensors



Find an ultrasonic distance-sensor and attach it to the 3D printed module.



Attach the ultrasonic distance-sensor to the robot.